

TITLE OF THE INVENTION  
CAMERA CONTROL SYSTEM AND METHOD,  
AND STORAGE MEDIUM

5 FIELD OF THE INVENTION

The present invention relates to a camera control system and method capable of controlling one or more video cameras connected to a network, and a storage medium.

10 BACKGROUND OF THE INVENTION

A camera control system capable of remotely controlling one or a plurality of monitoring cameras from a remote place has conventionally been known. In this system, either each camera is fixed to a camera platform  
15 to always direct to one direction, or its pan, tilt, and zoom can be externally controlled. The latter camera generally incorporates a function of remotely controlling the image sensing direction and magnification from a surveillance center.

20 In remotely controlling a plurality of cameras, the arrangement location and direction of each camera must be indicated to the operator. For example, the present applicant has already proposed a camera control system of displaying a graphic pattern (camera icon) representing a  
25 camera at a position corresponding to the installation position of each camera superposed on the map of a shop,



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There is provided a camera control system for selecting at least one of a plurality of controllable cameras connected to a network, and performing video display and camera control, comprising map display means, input means for designating one point on a map displayed by said map display means, camera selection means for selecting an optimal camera capable of monitoring the point designated by said input means, and camera control means for controlling the camera selected by said camera selection means.

A camera control method of the present invention is characterized by the following process according to its first aspect.

There is provided a camera control method of selecting at least one of a plurality of controllable cameras connected to a network, and performing video display and camera driving, comprising the display step of displaying a map on a display, the designation step of designating one point on the map displayed in the display step, the camera selection step of selecting an optimal camera capable of monitoring the point designated in the designation step, and the driving step of driving the camera selected in the camera selection step.

A storage medium of the present invention is characterized by the following arrangement according to its first aspect.

There is provided a storage medium storing a control program of selecting at least one of a plurality of controllable cameras connected to a network, and performing video display and camera driving, wherein the control  
5 program comprises a code of the display step of displaying a map on a display, a code of the designation step of designating one point on the map displayed in the display step, a code of the camera selection step of selecting an optimal camera capable of monitoring the point designated  
10 in the designation step, and a code of the driving step of driving the camera selected in the camera selection step.

Other objects and advantages besides those discussed above shall be apparent to those skilled in the art from the description of a preferred embodiment of the invention  
15 which follows. In the description, reference is made to accompanying drawings, which form a part hereof, and which illustrate an example of the invention. Such example, however, is not exhaustive of the various embodiments of the invention, and therefore reference is made to the claims  
20 which follow the description for determining the scope of the invention.

#### BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a schematic block diagram showing the basic  
25 arrangement of a computer system according to the first embodiment of the present invention;

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Fig. 2 is a schematic block diagram showing a hardware arrangement in a network;

Fig. 3 is a schematic block diagram showing a software arrangement in the network;

5 Fig. 4 is a view showing an example of a camera display control panel displayed on a display by a camera control client;

Fig. 5 is a flow chart showing processing by the camera control client;

10 Fig. 6 is a table for explaining the structure and contents of an area table;

Fig. 7 is a flow chart showing processing by a camera control server;

15 Fig. 8 is a view showing a specific area region in a map window in the second embodiment;

Fig. 9 is a flow chart showing processing additionally executed in the second embodiment;

Fig. 10 is a flow chart showing a camera selection method;

20 Figs. 11A and 11B are tables for explaining the structure and contents of a camera state table managed by a camera management server;

Fig. 12 is a view for explaining the image sensing direction and a image sensing range  $\theta_a$  ( $a, A$ ); and

25 Fig. 13 is a flow chart showing area table setting processing.

## DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Preferred embodiments of the present invention will be described in detail below with reference to the accompanying drawings.

(First Embodiment)

Fig. 1 is a block diagram showing the schematic arrangement of a video communication terminal serving as a basic element, i.e., a computer system connected to a plurality of cameras in the first embodiment of the present invention. One or more computers having the arrangement shown in Fig. 1 and/or one or more computers having a similar arrangement are connected to each other via a computer network.

In Fig. 1, reference numeral 10 (10-1, 10-2, 10-3,...) denote video cameras; 12 (12-1, 12-2, 12-3,...), camera control circuits for directly controlling the pan, tilt, zoom, focus adjustment, and stop value of the video cameras 10 (10-1, 10-2, 10-3,...) in accordance with external control signals; and 14, a camera input selection device for selecting which of the video cameras 10 is to be controlled, and which of their output signals (in general, video signals, but video and audio signals for a camera with a microphone) is to be received. An example of a control signal line is an RS-232C line, but the present invention is not limited to this.

Reference numeral 20 denotes a video communication terminal for sending a control command to a desired camera control circuit 12 via the camera input selection device 14 to control the video camera 10 corresponding to this camera control circuit 12, transmitting an image of a selected camera to the network, and receiving an image from the network; 22, a CPU for controlling the entire system; 24, a main storage; 26, a secondary storage (e.g., hard disk); 28, a mouse as a pointing device; and 30, a keyboard.

Reference numeral 32 denotes an I/O port connected to the camera input selection device 14 to supply a camera control command and the like to the camera input selection device 14; 34, a video board for receiving an output video signal from a video camera 10 selected by the camera input selection device 14, and displaying various images on a bitmap display 35; 36, a network interface for connecting the video communication terminal 20 to a computer network or communication network; and 38, a system bus for connecting the respective devices from the CPU 22 to the network interface 36 to each other. The network interface 36 can transmit a camera control signal from a remote place to the video communication terminal 20 via the network to control the video camera 10.

The camera input selection device 14 selects one of control signal lines connected to the camera control circuits 12 and one of video outputs, supplies the selected

video output to the video board 34, and logically connects the selected control signal line to the I/O port 32. An example of the video signal format is a luminance/color difference separation type NTSC signal format. The video  
5 board 34 receives the video output selected by the camera input selection device 14. The received video signal is displayed as a moving picture in a predetermined window on the bitmap display 35, and/or transmitted to another device.

10       The secondary storage 26 stores various pieces of information about the camera 10 or another camera connected via the network, e.g., camera position information data and camera graphic pattern data. Details of these pieces of information will be described later.

15       When only one camera 10 is connected, the camera input selection device 14 can be omitted, and the camera control circuit 12 can be directly connected to the I/O port 32. When no image is transmitted, the camera 10, camera control circuit 12, and camera input selection device 14 can be  
20 omitted.

      The apparatus shown in Fig. 1 is connected as a communication terminal to a network, as shown in Fig. 2. All the communication terminals need not have the same arrangement as that shown in Fig. 1. For example, the  
25 network may comprise a communication terminal connected to only one camera, or a terminal not connected to any camera



(i.e., a terminal having a function of only remotely controlling cameras connected to other terminals and displaying only an image from such cameras). In general, communication terminals having various arrangements  
5 coexist in one network. Note that the network adopted in this embodiment assumes a LAN or WAN having a transmission bandwidth wide enough to transmit digital moving picture data and a camera control signal. Moving picture data is generally compressed and transmitted. This embodiment can  
10 use various existing methods as a moving picture compression method, and a detailed description thereof will be omitted.

As described above, the video board 34 has a video capture function. The video board 34 supplies received  
15 video data to the bitmap display 35 to display an image, and in addition supplies the received video data to the CPU 22 via the bus 38. The CPU 22 packetizes the video data, and outputs the packet to the network via the network interface 36. A camera manipulation instruction and  
20 camera switching instruction are also packetized and transmitted to the network via the network interface 36. Information about the entire system is also packetized and transmitted to the network. These pieces of information are transmitted to a specific terminal or all terminals in  
25 accordance with the contents of data to be transmitted if needed.

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This also applies to reception. More specifically, when each video communication terminal 20 receives packetized video data, camera manipulation instruction, and camera switching instruction, the terminal 20 processes the received video data like capture data, and processes the received camera manipulation instruction and camera switching instruction like internal similar instructions. Information about the entire system is used to update the system display of a user interface (to be described below).

Fig. 3 is a block diagram showing a software arrangement in the first embodiment. In Fig. 3, a plurality of video communication terminals 20 and a camera management server 50 are connected to a computer network 52. A camera control server 54 for controlling the camera 10 in accordance with a camera control signal (including a selection signal when a plurality of cameras are connected) input from a self terminal or transmitted from another terminal, a camera control client 56 for remotely controlling the camera 10 of the self terminal or another terminal, and video transmission/reception software 58 for supplying an image from the camera of the self terminal to another terminal via the network 52, and supplying an image transferred from another terminal via the network 52 or an image from the camera 10 of the self terminal to the display 35 of the self terminal are installed in each video communication terminal 20.

The camera management server 50 is software for managing all cameras 10 released (or connected) to the network 52, and holds information such as the camera name, host name, installation position, and current status of  
5 each camera. The camera management server 50 manages registration of a camera newly usable via the network 52, and deletion along with disconnection from the network 52. In addition, the camera management server 50 informs all the camera control clients 56 of management information of  
10 each camera periodically or in accordance with a request. The camera management server 50 suffices to be stored in one of the terminals connected to the network 52.

The camera control client 56 displays the layout and directions of the camera 10 of the self terminal and all  
15 cameras usable via the network 52 by using predetermined camera symbols to be superposed on a map on the screen of the display 35 of the self terminal. The camera control client 56 updates the display state of each camera symbol in real time based on camera information periodically  
20 transmitted from the camera management server 50.

Fig. 4 is a view showing an example of a camera display control panel displayed on the display 35 by the camera control client 56. Reference numeral 60 denotes a map window for displaying a camera icon representing the  
25 installation position and direction of each camera superposed on a map showing the installation places of

controllable cameras; 62, a camera image window for displaying an image of one selected camera; and 64, a camera control panel which comprises various control buttons, and manipulates the pan, tilt, and zoom of a selected camera.

- 5 The first embodiment assumes that a window display system capable of simultaneously displaying a plurality of windows runs.

The map window 60 displays a map showing the seat layout of an office, and camera icons 66 representing the  
10 locations of respective cameras deployed in the office are displayed on the map. Each camera icon 66 is displayed in almost the same direction as the current camera direction at a position corresponding to the installation location of the corresponding camera. The camera icons 66 are  
15 displayed in different colors so as to identify a camera selected for video display or remote control, a camera used by another user, and a free camera.

The control panel 64 is displayed below the camera image window 62. The control panel 64 has two buttons, a  
20 rotation button for pan and tilt, and a zoom button. By operating these buttons, an arbitrarily designated camera can be rotated and zoomed. If a selected camera cannot be operated (for example, the camera is being operated by another user), both the rotation button and zoom button  
25 change to a control disable display state.

For example, when a user wants to access a certain

camera (in this case, remote control), the user double-clicks a camera icon representing this camera. Then, the camera control client 56 requests control of the camera of the camera management server 50. The camera management server 50 checks whether control of that camera has already been given to another user by referring to a camera status list (to be described later). If control of the camera is not assigned to another user, the camera management server 50 permits remote control of the camera (including video display as a matter of course); otherwise, denies control. If control is permitted, the camera image window 62 displays an output image from the camera to enable control (pan, tilt, and zoom) on the camera control panel 64.

Further, the first embodiment can select an optimal camera which can monitor a point on the map clicked (single-clicked in this embodiment) with a mouse, and control the camera so as to monitor the image at this point. For example, if the user clicks the mouse on the object of a door 80, the nearest camera 90 is controlled to face the door, and the image of the camera image window 62 is switched to an image from the camera 90. At this time, the display of the camera icon is changed to enable the user to easily know the camera he or she is controlling. For example, the camera icon is changed in color, or flickered for a predetermined time.

These operations are basically the same regardless of which of objects displayed on the map is designated. The present invention can select an optimal camera in consideration of the three-dimensional camera layout, image sensing range, camera use status, and the like. For example, if the user clicks the mouse on the object of a clock 81, a camera 92 at an optimal position for monitoring the clock is selected. There are two cameras 90 and 91 nearer the clock 81 than the camera 92. However, the camera 90 is outside the maximum field angle (doted line in Fig. 4, which is not displayed in practice), and cannot be actually directed to face the clock. Compared to the camera 91, the camera 92 can monitor the clock from its front side in terms of the layout. Although not apparent from the map because of two-dimensional display, the clock is hung high on the wall. The camera 92 is controlled not only to pan toward the clock 81 but also to tilt upward so as to clearly monitor the clock 81. If the camera 92 is controlled by another user, the camera 91 next optimal to monitor the clock 81 is selected. When the user clicks the mouse on the object of a safe 82, the nearest camera is a camera 94, but the camera 94 cannot monitor the safe 82 due to the presence of a wall 83. Thus, the second nearest camera 93 is controlled. Similarly, if the user clicks the icon of the camera 90 with the mouse, the nearest camera 91 is selected, and the user can see the status of the camera 90 (whether

the camera 90 has broken or operates) from a remote place by an image from the camera 91.

Note that if the user clicks an area (e.g., 85) other than objects on the map with the mouse, no operation starts  
5 in the first embodiment.

Processing for realizing camera control upon clicking the mouse on the map will be explained with reference to Figs. 5 to 7.

Fig. 5 shows processing by the camera control client.

10 The camera control client checks in step S51 whether the mouse has been clicked once, and, if YES in step S51, determines in step S52 whether the mouse was clicked on the map window 60. If NO in step S52, the same processing as normal one is done, and a description thereof will be  
15 omitted. If YES in step S52, the camera control client shifts to step S53, and checks from the coordinate position whether the mouse was clicked in a predetermined area. In this embodiment, the predetermined area includes objects (e.g., the door 80, clock 81, safe 82, and camera 90)  
20 displayed on the map.

If YES in step S53, the camera control client determines a camera optimal for monitoring the area (object) and its camera parameters with reference to an area table (Step 54: Fig. 6; to be described later). The camera  
25 parameters are the pan, tilt, and zoom in the first embodiment, but are not limited to them. The camera

parameters may be only the pan and tilt, or a combination of the focus and exposure information may be additionally used. In step S55, the camera control client transmits, to a camera control server for controlling the camera, a camera control request for controlling the camera to  
5 desired camera parameters. Then, the camera control client transmits a reception request command for the camera image to video transmission/reception software for transmitting the camera image.

10 Fig. 7 shows processing by the camera control server which has received the camera control request issued in step S55. The camera control server receives the camera control request in step S71, and executes camera control in step S72.

15 Fig. 6 shows details of the area table used in step S54. The area table is comprised of area numbers, camera IDs, and camera parameters. In the list of each area, an upper device has higher priority. For example, when the area 80 (i.e., door object 80) is designated on the map,  
20 the camera 90 is first selected as a control candidate. As the camera parameters, (pan angle, tilt angle, zoom ratio) = (0, 10, 2) is selected. If the camera 90 is being controlled by another user, the second listed camera 92 is selected. If the camera 92 is being controlled by another  
25 user, an error message such as "the camera cannot be controlled because it is being used by another user" is



displayed in a message region 90 in Fig. 4. Whether a camera is being controlled can be determined by an inquiry sent from the camera control client to the camera management server.

5           Fig. 13 shows an area table setting processing flow.

          In this processing, a different table may be set for the camera control client of each video communication terminal. Alternatively, a privileged user (manager) of this surveillance system may set an area table at a specific  
10 video communication terminal, and the set area table may be reflected on all camera control clients.

          This processing can be set by switching a normal surveillance mode to a setting mode using the same user interface as that in Fig. 4. In the setting mode, camera  
15 control or the like is temporarily locked to deny any other access.

          In step S131, an area to be set is designated in the map window 60. If an area is partitioned for each object, the area is designated. Alternatively, a rectangular  
20 frame which contains the object and has a minimum area may be designated with the mouse. In step S132, a camera which is to be moved when the area designated in step S131 is clicked with the mouse is selected. Then, the direction, field angle, and zoom of the camera can be controlled on  
25 the control panel 64, and an image from the camera is displayed on the camera image window 62. The user controls

the camera so as to clearly monitor the area (object) (step S133). After proper camera parameters are set, the user clicks a "setting" button (not shown), and then the area table is updated in step S134. This control (from step S132  
5 to step S134) is performed in order of cameras to be actually moved in the normal surveillance mode. Note that when a camera whose camera parameters have been set once is clicked again, the parameters of this camera in the area table are rewritten.

10 Accordingly, the user interface as shown in Fig. 4 can be implemented by registering in advance camera parameter information about a camera to be selected and its direction and zoom ratio upon designating an object displayed on the map.

15 (Second Embodiment)

In the first embodiment, when only a specific object displayed on a map is designated, a corresponding camera is selected and controlled. In the second embodiment, a designated portion is not limited to an object. As shown  
20 in Fig. 8, rectangular regions having various areas are set as specific areas. When the mouse is clicked in such an area, an optimal camera is selected and controlled so as to photograph an object designated in advance in the selected area.

25 For example, irrespective of the position in a vault 84 on the map which is clicked, a camera 93 can be immediately

directed to a safe 82 which most characterizes the vault.  
(Third Embodiment)

In the first embodiment, if a region other than a specific area on a map is designated, like step S53 in Fig. 5,  
5 no operation starts. This is effective when a person who manages a camera (camera manager) feels troublesome to determine cameras optimal for monitoring respective regions on a map and their camera parameters for any arbitrary coordinates with the mouse (because only partial  
10 regions on the map suffice to be set).

However, some users want to direct a camera to a point (e.g., 85 in Fig. 4) where no object is displayed on the map and to see the image. In the third embodiment, this processing is compensated on the system side without  
15 setting in advance any area table for all the coordinates on the map by the camera manager.

This embodiment is additionally executed when the mouse is determined in step S53 of Fig. 4 to be clicked outside a predetermined area. Only the additional  
20 processing will be explained with reference to Figs. 9 to 12.

In step S91, a camera to be controlled is selected from a coordinate position clicked with the mouse on the map. In step S92, the moving amount of the camera to monitor  
25 the clicked point is calculated. For example, a moving amount for directing the center of the camera to a direction

in which the position clicked on the map and the camera selected in step S91 are connected by a straight line is calculated (if the moving amount exceeds the maximum pan range, the zoom ratio is minimized). In step S93, the  
5 calculated moving amount is transmitted as a camera control command to the camera control server of the camera.

Fig. 10 is a flow chart showing a camera selection method in step S91 of Fig. 9. In step S101, the distances between a position (a) clicked on the map and all camera  
10 icon coordinates are calculated. In step S102, a camera corresponding to an icon nearest to the position a is selected as a candidate camera (camera x). In step S103, whether the straight line which connects the position a and camera x falls within the visible range (field range  
15 obtained when the zoom ratio is minimized and the camera is panned maximally) of the camera x is checked. At this time, whether the position a cannot be seen from the camera due to an obstacle such as a wall between a and x is also checked. The visible range is obtained with reference to  
20 Fig. 11A or 11B showing a camera state table integrally managed by the camera management server.

Figs. 11A and 11B are tables showing the structure and contents of the camera state table.

Figs. 11A and 11B show examples of the camera state  
25 table which stores fixed information and variable information of each camera. Fig. 11A shows a camera state

table for fixed information, and Fig. 11B shows a camera state table for storing the current value of variable information.

The camera state table shown in Fig. 11A includes the  
 5 camera number, camera name, host name, camera installation position coordinates on the map, initial direction at the start, maximum zoom ratio, maximum field angle (field angle when the zoom ratio is minimized), and pannable direction  $\theta_p$  ( $p < \theta_p < P$ ) representing a pannable range.  $\theta_p$ ,  $p$ ,  
 10 and  $P$  are the angles with respect to the x direction (horizontal direction).

The camera state table shown in Fig. 11B has the camera number, current zoom ratio, current video field angle (obtained by referring to a correspondence table of  
 15 the zoom ratio and video field angle using a current zoom ratio, as needed), current image sensing direction, and current image sensing range  $\theta_a$  ( $a < \theta_a < A$ ). The image sensing range  $\theta_a$  can be calculated from the video field angle and the current image sensing direction. As shown  
 20 in Fig. 12, letting  $\alpha$  be the video field angle, and  $\Phi$  be the current image sensing direction,

$$a = \Phi - \alpha/2$$

$$A = \Phi + \alpha/2$$

where  $a$  and  $A$  are the angles with respect to the x direction  
 25 (horizontal direction).

Note that the camera management server integrally

manages information such as camera layout information,  
current direction, and field angle by using the camera state  
table as shown in Fig. 11A or 11B. Alternatively, the  
camera control server of the video communication terminal  
5 of a camera may manage the information in units of cameras.

Referring back to Fig. 10, if YES in step S103,  
whether the camera x is being controlled by another user  
is checked in step S104. If NO in step S103 or S104, the  
camera x cannot monitor the current point a, and the  
10 processing returns to step S102 to select the next candidate  
camera. In this case, a camera having the second shortest  
distance is selected as a candidate. Then, the processing  
shifts to step S105 to determine the camera.

The flow chart in Fig. 10 shows the processing method  
15 of selecting a camera icon nearest to the position a clicked  
with the mouse and controlling the camera. In addition to  
this processing, the step of checking whether a camera  
directed to the position a currently exists with reference  
to variable information of the camera in Fig. 11, and if  
20 a camera directed to the position a exists, shifting to step  
S105 to determine the camera as a candidate may be adopted  
as step S100 before step S101. If a camera directed to the  
position a exists, this step can omit the control time for  
calculating the distances of all cameras and the control  
25 time for directing a camera to the position a.

(Fourth Embodiment)

In the first embodiment, one camera optimal for monitoring an area (object) is selected with reference to the area table (Fig. 6) in step S54 of Fig. 5, and the camera is controlled to display an image. In addition to the  
5 arrangements of the first to third embodiments, the fourth embodiment has a mode in which a plurality of cameras capable of monitoring an object are selected, and all the selected cameras are directed to a point clicked with the mouse on a map. Switching of the mode is achieved by newly  
10 adding a mode switching window on the display screen of Fig. 4.

For example, when the user clicks the mouse on an object 81 (clock) in a map window 60, the area table in Fig. 6 is referred to to issue a camera control request to the  
15 camera control server so as to set predetermined camera parameters in all cameras (in this case, cameras 92 and 91) registered for the object 81. In this case, a camera image window 62 in Fig. 4 can display a plurality of images. This arrangement can control a plurality of cameras by only one  
20 object designation, and confirm an object from various angles.

As is apparent from the above description, the above embodiments can control a camera to actually monitor an object on a map designated with a mouse. At this time, a  
25 camera optimal for monitoring the object and its camera parameters can be set with a simple user interface. If this

camera is being controlled by another user, the next candidate camera is selected to monitor the point.

Even when the user clicks with the mouse not only an object but also a given region (area) on the map, a camera  
5 optimal for monitoring the area can be selected to monitor the state of the area.

If the user clicks with the mouse an area other than a predetermined area on the map, no operation starts.

Moreover, even if the user clicks with the mouse an  
10 area other than a predetermined area on the map, the nearest camera capable of image sensing the designated point can be selected and directed to the point without setting an optimal camera and its camera parameters.

When the user clicks a predetermined area on the map  
15 with the mouse, a plurality of cameras can monitor the point.

The object of the present invention is realized even by supplying a storage medium (or recording medium) storing software program codes for realizing the functions of the  
20 above-described embodiments to a system or apparatus, and causing the computer (or a CPU or MPU) of the system or apparatus to read out and execute the program codes stored in the storage medium. In this case, the program codes read out from the storage medium realize the functions of the  
25 above-described embodiments by themselves, and the storage medium storing the program codes constitutes the present



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invention. The functions of the above-described  
embodiments are realized not only when the readout program  
codes are executed by the computer but also when the operating  
system (OS) running on the computer performs part or all of  
5 actual processing on the basis of the instructions of the  
program codes.

The functions of the above-described embodiments are  
also realized when the program codes read out from the storage  
medium are written in the memory of a function expansion card  
10 inserted into the computer or a function expansion unit  
connected to the computer, and the CPU of the function  
expansion card or function expansion unit performs part or  
all of actual processing on the basis of the instructions  
of the program codes.

15 When the present invention is applied to the above  
storage medium, the storage medium stores program codes  
corresponding to the above-described flow charts (shown in  
Figs. 5, 7, 9, 10, and 13).

As has been described above, the present invention  
20 can improve the camera control operability on a map.

The present invention is not limited to the above  
embodiments and various changes and modifications can be  
made within the spirit and scope of the present invention.  
Therefore, to apprise the public of the scope of the present  
25 invention the following claims are made.